



Ampere-Maxwell law for magnetic field circulation

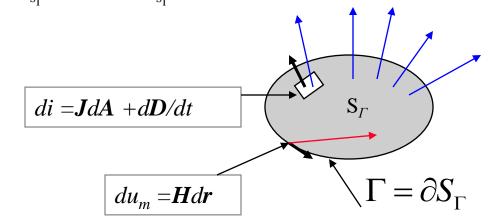
$$u_{m\Gamma} = i_{S\Gamma} + \frac{d\psi_{S\Gamma}}{dt} \Leftrightarrow$$

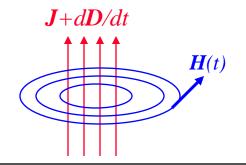
$$\oint_{\Gamma} \mathbf{H} d\mathbf{r} = \int_{S_{\Gamma}} \mathbf{J} d\mathbf{A} + \frac{d}{dt} \int_{S_{\Gamma}} \mathbf{D} d\mathbf{A}$$

- 1. Global (integral) form of the law:
- 2. Physical meaning:

Any conductor carrying current produces a magnetic field. The time variation of electric field generates as well a magnetic field, it was called by Maxwell the "displacement current".

- 3. The lines of the generated magnetic field
- Are closed curves
- They are turned around the electric or displacement current.
- Their direction is dependent of the current direction.







Local forms of Ampere-Maxwell law in fixed (not mobile) bodies

- Local (differential) form of the law:
- $curl\mathbf{H} = \mathbf{J} + \underbrace{\partial \mathbf{D}}_{\partial t} \Leftrightarrow \nabla \times \mathbf{E} = \mathbf{J}_{t}$ \mathbf{J}_{d} $\mathbf{J} + \mathbf{J}_{d}$

2. Proof (based on Stokes theorem):

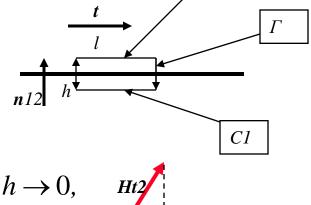
$$\oint_{\Gamma} \mathbf{H} d\mathbf{r} = \int_{s_{\Gamma}} curl \mathbf{H} d\mathbf{A} = \int_{s_{\Gamma}} \mathbf{J} d\mathbf{A} + \frac{d}{dt} \int_{s_{\Gamma}} \mathbf{D} d\mathbf{A} = \int_{s_{\Gamma}} (\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}) d\mathbf{A}, \forall S_{\Gamma} \uparrow \uparrow$$

3. Conservation of the tangential component of the magnetic field strength

$$\oint_{\Gamma} \mathbf{H} d\mathbf{r} = \oint_{C_1} \mathbf{H} d\mathbf{r} + \oint_{C_2} \mathbf{H} d\mathbf{r} = \mathbf{t} \cdot (\mathbf{H}_2 - \mathbf{H}_1)_{ave} l,$$

$$\int_{S_{\Gamma}} \mathbf{J} d\mathbf{A} + \frac{d}{dt} \int_{S_{\Gamma}} \mathbf{D} d\mathbf{A} = (J_{nave} + \frac{dD_{nave}}{dt})lh \to J_{s}l, \text{ when } h \to 0,$$

$$\Rightarrow$$
 $\mathbf{n}_{12} \times (\mathbf{H}_2 - \mathbf{H}_1) = \mathbf{J}_s \Rightarrow \mathbf{H}_{t2} = \mathbf{H}_{t1}, \text{ if } \mathbf{J}_s = 0.$



Ht1

*C*2



Local and developed integral forms in mobile bodies

- Local (differential) form of the law:

1. Local (differential) form of the law:

$$curl \ \mathbf{H} = \mathbf{J} + \frac{d_f \mathbf{D}}{dt} \Leftrightarrow$$
2. Proof, based on Stokes theorem and flux derivative:
$$curl \ \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \Leftrightarrow$$

$$curl \ \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} + \rho \mathbf{v} + curl(\mathbf{D} \times \mathbf{v})$$

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$$\int_{S} (\mathbf{v} div \mathbf{D} + curl(\mathbf{D} \times \mathbf{v})) d\mathbf{A}, \frac{d}{dt} \int \mathbf{D}(t) d\mathbf{A} = \int \frac{\partial \mathbf{D}(t)}{\partial t} d\mathbf{A}, \Rightarrow \frac{d}{dt} \int \mathbf{D}(t) d\mathbf{A} = \int \frac{d_f \mathbf{D}(t)}{dt} d\mathbf{A},$$

where
$$\frac{d_f \mathbf{D}(t)}{dt} = \int_{def} \frac{\partial \mathbf{D}}{\partial t} + \mathbf{v} div \mathbf{D} + curl(\mathbf{D} \times \mathbf{v}), curl \mathbf{H} = \mathbf{J} + \frac{d_f \mathbf{D}}{dt}; div \mathbf{D} = \rho \Rightarrow$$

$$curl \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} + \rho \mathbf{v} + curl(\mathbf{D} \times \mathbf{v}) \Rightarrow \int_{\Gamma} (-\mathbf{H} + \mathbf{D} \times \mathbf{v}) d\mathbf{r} + \int_{S_{\Gamma}} (\rho \mathbf{v} + \frac{\partial \mathbf{D}}{\partial t}) d\mathbf{A} = 0$$
integral form

$$curl\mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} + \rho \mathbf{v} + curl(\mathbf{D} \times \mathbf{v}) \Rightarrow \oint_{\Gamma} (-\mathbf{H} + \mathbf{D} \times \mathbf{v}) d\mathbf{r} + \int_{S_{\Gamma}} (\rho \mathbf{v} + \frac{\partial \mathbf{D}}{\partial t}) d\mathbf{A} = 0$$

integral form

Densities of: Conduction, Displacement, Convection and Rontgen currents



Ampere theorem. The static case

In static fields and not mobile bodies:

- **Global form**
- **Local (differential) form**
- In Cartesian coordinates:
- Dependence of the magnetic voltage from the integration path

$$u_{m\Gamma} = i_{S\Gamma} \iff \oint_{\Gamma} \mathbf{H} d\mathbf{r} = \int_{S_{\Gamma}} \mathbf{J} dA, \forall S_{\Gamma}$$

$$curl\mathbf{H} = \mathbf{J} \Leftrightarrow \nabla \times \mathbf{H} = \mathbf{J}$$

Proof:
$$curl\mathbf{H} = \mathbf{J} + \mathbf{D} = \mathbf{J}$$
 $curl\mathbf{H} = \nabla \times \mathbf{H} = \begin{bmatrix} \mathbf{I} & \mathbf{J} & \mathbf{K} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ H_x & H_y & H_z \end{bmatrix} = \mathbf{J}$
Dependence of the magnetic

$$u_{m\Gamma} = \oint_{\Gamma} \mathbf{H} d\mathbf{r} = \int_{C1} \mathbf{H} d\mathbf{r} + \int_{C2} \mathbf{H} d\mathbf{r} = \int_{C1} \mathbf{H} d\mathbf{r}_{1} - \int_{C2} \mathbf{H} d\mathbf{r}_{2} = u_{1} - u_{2} = i_{S\Gamma} \Rightarrow$$

 $u_1 = u_2 \forall C_1, C_2 \text{ with } \partial C_1 = \partial C_2 = \{A, B\} \text{ only if } \mathbf{J} = 0.$

In this case may be defined the scalar magnetic potential: $\mathbf{H} = -gradV_m$



Application of the Ampere law

Magnetic field produced by current in a cylinder

$$u_{m\Gamma} = \oint_{\Gamma} \mathbf{H} d\mathbf{r} = H \int_{\Gamma} dr = H 2\pi r,$$

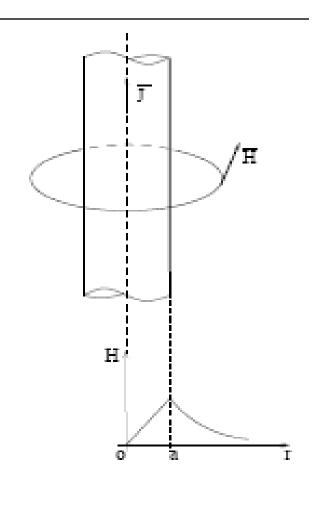
$$i_{S\Gamma} = \int_{S_{\Gamma}} \mathbf{J} d\mathbf{A} = J \int_{S_{\Gamma}} dA = J \pi r^2$$
, for $r < a$

$$u_{m\Gamma} = i_{S\Gamma} \Longrightarrow H = Jr / 2$$

For
$$r > a, i_{S\Gamma} = \int_{S_{\Gamma}} J dA = \int_{S_{\Gamma}} J dA = J \pi a^2 = I$$
,

$$H = \frac{Ja^2}{2r} = \frac{I}{2\pi r}$$

$$H(r) = \begin{cases} \frac{Jr}{2} = \frac{Ir}{2\pi a^2}, & \text{for } r < a \\ \frac{Ja^2}{2r} = \frac{I}{2\pi r}, & \text{for } r > a \end{cases}$$



An uniform time variable electric field D(t) produces same magnetic field if J = dD/dt.



Several forms of the Ampere's law

Movement	No	Yes
Global	$u_{m\Gamma} = i_{S\Gamma} + \frac{d\psi_{S\Gamma}}{dt}$	$u_{m\Gamma} = i_{S\Gamma} + \frac{d\psi_{S\Gamma}}{dt}$
Integral	$ \oint_{\Gamma} \mathbf{H} d\mathbf{r} = \mathbf{J} + \frac{d}{dt} \int_{s_{\Gamma}} \mathbf{D} d\mathbf{A} $	$\oint_{\Gamma} \mathbf{H} d\mathbf{r} = \mathbf{J} + \frac{d}{dt} \int_{s_{\Gamma}} \mathbf{D} d\mathbf{A}$
Developed integral	$\oint_{\Gamma} \mathbf{H} d\mathbf{r} = \mathbf{J} + \int_{s_{\Gamma}} \frac{\partial \mathbf{D}}{\partial t} d\mathbf{A}$	$ \int_{\Gamma} \mathbf{H} d\mathbf{r} = \int_{S_{\Gamma}} (\mathbf{J} + \rho \mathbf{v} + \frac{\partial \mathbf{D}}{\partial t}) d\mathbf{A} + \int_{\Gamma} (\mathbf{D} \times \mathbf{v}) d\mathbf{r} $
On surfaces	$\mathbf{n}_{12} \times (\mathbf{H}_2 - \mathbf{H}_1) = \mathbf{J}_s$	$\mathbf{n}_{12} \times [(\mathbf{H} + \mathbf{D} \times \mathbf{v})_2 - (\mathbf{H} + \mathbf{D} \times \mathbf{v})_2] = 0$
Conserv.	$\mathbf{H}_{t1} = \mathbf{H}_{t2}$	-
Field lines	Turned around the current	-



Not so easy questions for curious people

- What do the surface S_r(t) in the moving bodies ? Is it fixed or carry on by the moving body ?
- 2. Is still valid the H tangential component conservation in the case of a sheet carrying conduction/displacement current?
- 3. Why the expression of the Roengen current density was not confirmed by measurements?