

Electromagnetic Modeling

12. Magneto-Quasi-Static Field

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- 1. Hypothesis, First order equations**
- 2. Second order equation: scalar and vector potentials**
- 3. A-V and T-Vm formulations**
- 4. Fundamental problem, initial and boundary conditions**
- 5. Eddy current problems**
- 6. Weak formulations**
- 7. Applications**
- 8. Questions**

MQS-Magneto-Quasi-Static Field

Slow time variation.
Displacement current and
charge relaxation are
neglected

$$1. \nabla \cdot \mathbf{D} = \rho$$

$$2. \nabla \cdot \mathbf{B} = 0$$

$$3. \nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$4. \nabla \times \mathbf{H} = \mathbf{J} + \cancel{\frac{\partial \mathbf{D}}{\partial t}}$$

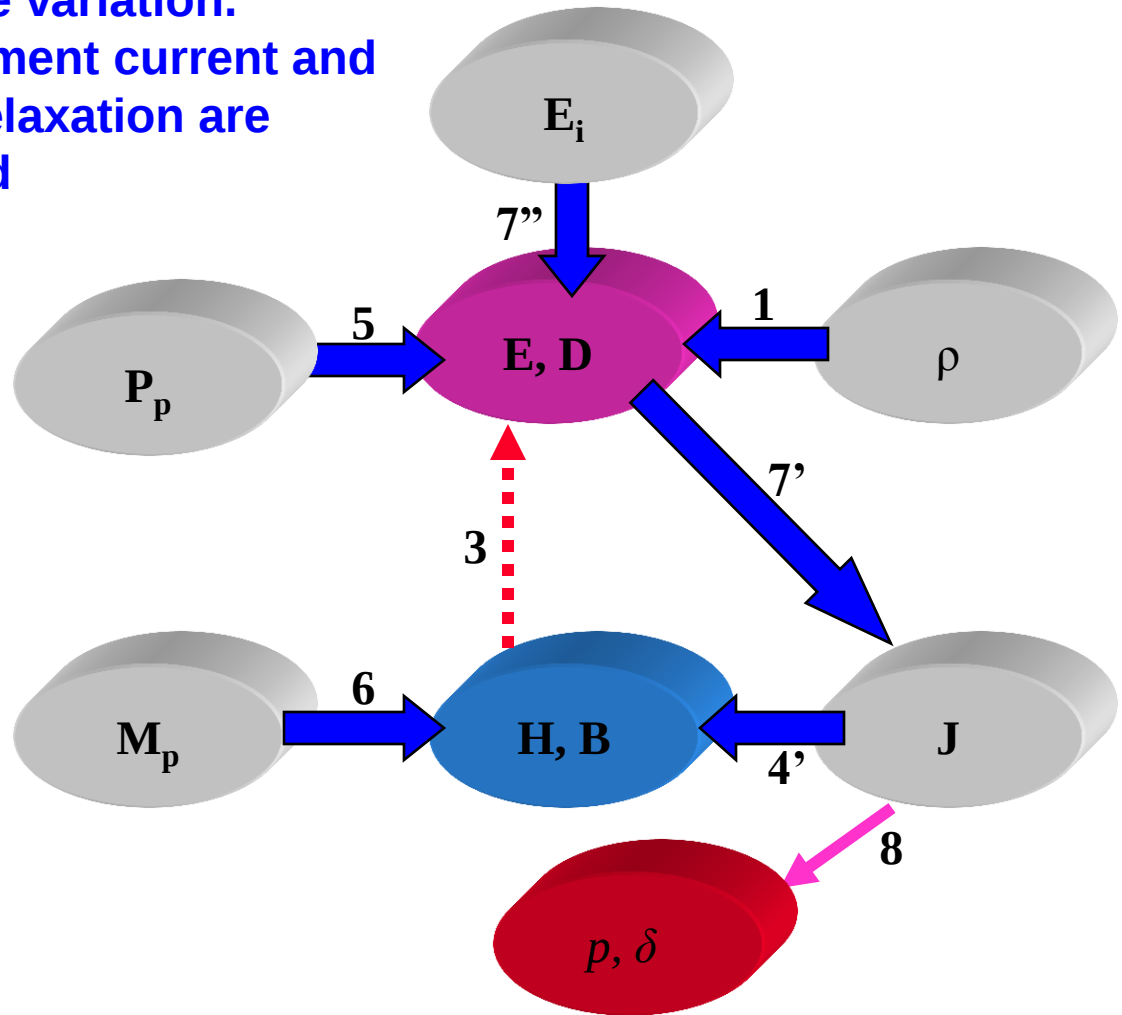
$$5. \mathbf{D} = \varepsilon \mathbf{E} + \mathbf{P}_p(\mathbf{E})$$

$$6. \mathbf{B} = \mu (\mathbf{H} + \mathbf{M}_p(\mathbf{H}))$$

$$7. \mathbf{J} = \sigma(\mathbf{E} + \mathbf{E}_i(\mathbf{E}))$$

$$8. p = \mathbf{E} \mathbf{J}$$

$$9. \nabla \cdot \mathbf{J} = -\cancel{\frac{\partial \rho}{\partial t}}$$



MQS equations

- Hypothesis:**

- no movement
- slow time variation
- capacitive effects are neglected

- Fundamental Equations:**

- Gauss' theorem**

- Ampere's theorem**

- Magnetic and conductive constitutive relations**

- Induction law**

$$u_{\Gamma} = -\frac{d\varphi_{S_{\Gamma}}}{dt} \Leftrightarrow \oint_{\Gamma} \mathbf{E} d\mathbf{r} = -\frac{d}{dt} \int_{S_{\Gamma}} \mathbf{B} \cdot \mathbf{n} dS \Rightarrow \text{curl} \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \Rightarrow \text{curl}_s \mathbf{E} = 0$$

- Field sources:**

- Conduction current

- MQS field is similar to MG+EC, but J is unknown**

$$\left\{ \begin{array}{l} \Phi_{\Sigma} = 0 \Leftrightarrow \oint_{\Sigma} \mathbf{B} d\mathbf{A} = 0 \\ \text{div} \mathbf{B} = 0 \Rightarrow \mathbf{B} = \text{curl} \mathbf{A} \\ \mathbf{n}_{12} \cdot (\mathbf{B}_2 - \mathbf{B}_1) = 0 \Leftrightarrow \text{div}_s \mathbf{B} = 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} u_{m\Gamma} = i_{S_{\Gamma}} \Leftrightarrow \oint_{\Gamma} \mathbf{H} d\mathbf{r} = \int_{S_{\Gamma}} \mathbf{J} \cdot \mathbf{n} dS \\ \text{curl} \mathbf{H} = \mathbf{J} \Rightarrow \text{div} \mathbf{J} = 0 \\ \mathbf{n}_{12} \times (\mathbf{H}_2 - \mathbf{H}_1) = 0, \Leftrightarrow \mathbf{H}_{t2} = \mathbf{H}_{t1} \end{array} \right.$$

$$\mathbf{B} = f(\mathbf{H}) \Rightarrow \mathbf{B} = \mu_0(\mathbf{H} + \mathbf{M}) \Rightarrow \mathbf{B} = \mu \mathbf{H} + \mu_0 \mathbf{M}_p$$

$$\mathbf{J} = g(\mathbf{E}) \Rightarrow \mathbf{J} = \sigma(\mathbf{E} + \mathbf{E}_i) \Rightarrow \mathbf{J} = \sigma \mathbf{E} + \mathbf{J}_i$$

MQS:	H,E	B,J	J_i	μ, σ	A,V
MG:	H	B	J	μ	A
EC:	E	J	-	σ	V

MQS equations – AV formulation

- First order:

$$\left\{ \begin{array}{l} \operatorname{div} \mathbf{B} = 0 \\ \operatorname{rot} \mathbf{H} = \mathbf{J} \Rightarrow \operatorname{div} \mathbf{J} = 0 \\ \operatorname{rot} \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \\ \mathbf{B} = \mu \mathbf{H} + \mathbf{B}_r \\ \mathbf{J} = \sigma \mathbf{E} + \mathbf{J}_i \end{array} \right.$$

- On surfaces:

$$\left\{ \begin{array}{l} \operatorname{div}_s \mathbf{B} = 0 \Rightarrow B_{n1} = B_{n2}; \operatorname{div}_s \mathbf{A} = 0 \Rightarrow A_{n1} = A_{n2} \\ \operatorname{rot}_s \mathbf{H} = \mathbf{J}_s \Leftrightarrow \mathbf{H}_{t2} = \mathbf{H}_{t1}; \operatorname{rot}_s \mathbf{A} = 0 \Rightarrow \mathbf{A}_{t2} = \mathbf{A}_{t1} \\ \Rightarrow \mathbf{n} \times \nu_2 \operatorname{rot} \mathbf{A}_2 = \mathbf{n} \times \nu_1 \operatorname{rot} \mathbf{A}_1 \Leftrightarrow \operatorname{rot}_s (\nu \operatorname{rot} \mathbf{A}) = 0 \\ \operatorname{rot}_s \mathbf{E} = 0 \Leftrightarrow \mathbf{E}_{t2} = \mathbf{E}_{t1} \Rightarrow V_1 = V_2 \\ \operatorname{div}_s \mathbf{J} = 0 \Rightarrow J_{n1} = J_{n2} \Rightarrow \sigma_1 dV_1 / dn = \sigma_2 dV_2 / dn \end{array} \right.$$

- Second order: $\operatorname{div} \mathbf{B} = 0 \Rightarrow \mathbf{B} = \operatorname{rot} \mathbf{A}$; $\operatorname{div} \mathbf{A} = 0$? **Coulomb g.c.**

$$\left\{ \begin{array}{l} \operatorname{rot} \mathbf{H} = \mathbf{J} \Rightarrow \operatorname{rot} \nu (\mathbf{B} - \mathbf{B}_r) = \sigma \mathbf{E} + \mathbf{J}_i \Rightarrow \operatorname{rot} \nu \mathbf{B} = \operatorname{rot} (\nu \mathbf{B}_r) + \sigma \mathbf{E} + \mathbf{J}_i \\ \operatorname{rot} \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \Rightarrow \operatorname{rot} \mathbf{E} + \operatorname{rot} \frac{\partial \mathbf{A}}{\partial t} = 0 \Rightarrow \mathbf{E} + \sigma \frac{\partial \mathbf{A}}{\partial t} = -\operatorname{grad} V \\ \mathbf{B} = \mu \mathbf{H} + \mathbf{B}_r \Rightarrow \mathbf{H} = \nu (\mathbf{B} - \mathbf{B}_r) \\ \mathbf{J} = \sigma \mathbf{E} + \mathbf{J}_i \Rightarrow \operatorname{div} (\sigma \mathbf{E}) = 0 \Rightarrow \operatorname{div} (\sigma \operatorname{grad} V) + \operatorname{div} \left(\sigma \frac{\partial \mathbf{A}}{\partial t} \right) = 0 \Rightarrow \Delta V = 0 \\ \operatorname{rot} (\nu \operatorname{rot} \mathbf{A}) = \operatorname{rot} (\nu \mathbf{B}_r) + \sigma \mathbf{E} + \mathbf{J}_i \Rightarrow \operatorname{rot} (\nu \operatorname{rot} \mathbf{A}) + \sigma \left(\frac{\partial \mathbf{A}}{\partial t} + \operatorname{grad} V \right) = \operatorname{rot} (\nu \mathbf{B}_r) + \mathbf{J}_i \end{array} \right. \Rightarrow \text{Parabolic equations!}$$

MQS equations - TVm (TΩ) formulation

- **First order:**

$$\left\{ \begin{array}{l} \operatorname{div} \mathbf{B} = 0; \operatorname{rot} \mathbf{H} = \mathbf{J} \\ \operatorname{rot} \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \\ \mathbf{B} = \mu \mathbf{H} + \mathbf{B}_r; \\ \mathbf{J} = \sigma \mathbf{E} + \mathbf{J}_i \end{array} \right.$$

- **Second order:**

$$\left\{ \begin{array}{l} \operatorname{div} \mathbf{B} = 0 \Rightarrow \operatorname{div}(\mu \mathbf{H} + \mathbf{B}_r) = 0 \Rightarrow \operatorname{div}(\mu \mathbf{T} - \mu \operatorname{grad} V_m + \mathbf{B}_r) = 0 \Rightarrow \Delta V_m = -v \operatorname{div} \mathbf{B}_r \\ \operatorname{rot} \mathbf{H} = \mathbf{J} \Rightarrow \operatorname{div} \mathbf{J} = 0 \Rightarrow \mathbf{J} = \operatorname{rot} \mathbf{T}; \operatorname{div} \mathbf{T} = 0 \Rightarrow \\ \operatorname{rot}(\mathbf{H} - \mathbf{T}) = 0 \Rightarrow \mathbf{H} - \mathbf{T} = -\operatorname{grad} V_m \Rightarrow \mathbf{H} = \mathbf{T} - \operatorname{grad} V_m \\ \operatorname{rot} \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \Rightarrow \operatorname{rot}(\rho(\operatorname{rot} \mathbf{T} - \mathbf{J}_i)) = \frac{\partial \mathbf{B}}{\partial t} \Rightarrow \\ \mathbf{B} = \mu \mathbf{H} + \mathbf{B}_r \Rightarrow \operatorname{rot}(\rho(\operatorname{rot} \mathbf{T} - \mathbf{J}_i)) = \mu \frac{\partial \mathbf{H}}{\partial t} \\ \mathbf{J} = \sigma \mathbf{E} + \mathbf{J}_i \Rightarrow \mathbf{E} = \rho(\mathbf{J} - \mathbf{J}_i) \Rightarrow \mathbf{E} = \rho(\operatorname{rot} \mathbf{T} - \mathbf{J}_i) \end{array} \right.$$

$$\operatorname{rot}(\rho(\operatorname{rot} \mathbf{T} - \mathbf{J}_i)) = \mu \frac{\partial \mathbf{H}}{\partial t} \Rightarrow \operatorname{rot}(\rho \operatorname{rot} \mathbf{T}) - \mu \frac{\partial \mathbf{T}}{\partial t} + \mu \operatorname{grad} \frac{\partial V_m}{\partial t} = \operatorname{rot}(\rho \mathbf{J}_i)$$

- **On surfaces:**

$$\left\{ \begin{array}{l} \operatorname{div}_s \mathbf{T} = 0 \Rightarrow T_{n1} = T_{n2}; \\ \operatorname{rot}_s \mathbf{T} = \mathbf{J}_s \Rightarrow \mathbf{T}_{t2} = \mathbf{T}_{t1}; \operatorname{rot}_s(\mathbf{E}) = \operatorname{rot}_s(\rho \operatorname{rot} \mathbf{T}) = 0 \\ \mathbf{H} = \mathbf{T} - \operatorname{grad} V_m \Rightarrow \\ V_{m1} = V_{m2}; \mu_2 dV_{m2} / dn = \mu_1 dV_{m1} / dn \end{array} \right.$$

Boundary conditions for AV formulation

- Magnetic vector potential (parabolic, gen. diffusion vect. eq.):

$$\text{rot}(\nu \text{rot} \mathbf{A}) + \text{grad}(\nu \text{div} \mathbf{A}) + \sigma \left(\frac{\partial \mathbf{A}}{\partial t} + \text{grad} V \right) = \text{rot}(\nu \mathbf{B}_r) + \mathbf{J}_i$$

- Electric scalar potential (gen. Laplace eq.): with Coulomb gauge condition

$$\text{div}(\sigma \text{grad} V) + \text{div}(\sigma \frac{\partial \mathbf{A}}{\partial t}) = 0; \text{div}(\sigma \mathbf{A}) = 0 \Rightarrow \text{div}(\sigma \text{grad} V) = 0$$

$$\sigma = ct \Rightarrow \text{div} \mathbf{A} = 0; \Delta V = 0, \text{ with } V = f(P) \text{ on } S_D; dV/dn = j_n(P) \text{ on } S_N$$

Vector boundary conditions are necessary for a unique solution

Dirichlet b.c.

Neumann b.c.

$$\mathbf{A}_t(P) = \mathbf{f}_{DA}(P), \text{ on } S_B \neq \emptyset$$

$$\nu \mathbf{n} \times (\text{curl} \mathbf{A} \times \mathbf{n}) = \mathbf{f}_{NA}(P) = \mathbf{h}_t, \text{ on } S_H = \Sigma - S_B$$

For a unique vector potential A:

If

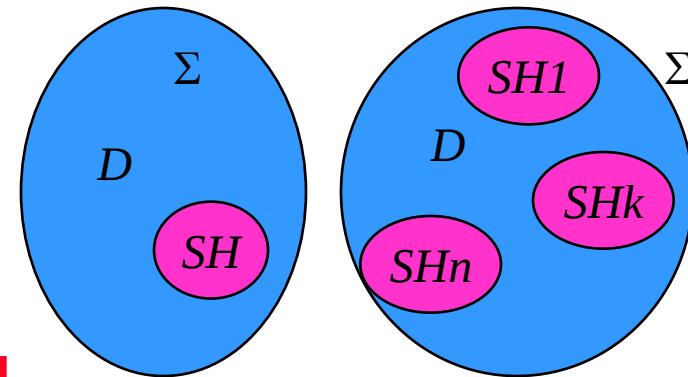
$$\mathbf{n} \cdot \mathbf{A} = A_n(P), \text{ on } S_H$$

$$S_H = \bigcup_{k=1}^m S_k \text{ multipleconnex} \Rightarrow \int_{S_k} \mathbf{B} \cdot d\mathbf{S} = \varphi_k \text{ or } \int_{C_{km}} \mathbf{H} \cdot d\mathbf{r} = u_k; k = 1, \dots, m-1$$

The fundamental MQS problem in terms of fields

Input (known) data:

- Computational domain D bounded by Σ
- (CM) Material characteristics $\sigma, \mu(\mathbf{r}) > 0$ in D
- (CD) Internal field sources $\mathbf{J}_i(\mathbf{r})$ in D
- (C Σ') Boundary conditions



$\mathbf{E}_t(\mathbf{r})$ on SD connected and $\mathbf{J}_n(\mathbf{r})$ on $SN = \Sigma - SD$

$\mathbf{H}_t(\mathbf{r})$ on SH connected and $\mathbf{B}_n(\mathbf{r})$ on $SB = \Sigma - SH$

– (IC) Initial conditions: $\mathbf{B}(\mathbf{r})$ on D

For non-connected Dirichlet surfaces $S_H = \bigcup_{k=1}^n S_{Hk}, S_{Hk} \cap S_{Hj} = \emptyset$
in addition to (C Σ') solution uniqueness requires :

(C Σ'') $U_k = \int_{PkP_0} \mathbf{H}_t d\mathbf{r}$ or $\Phi_k = \int_{S_{Hk}} \mathbf{B}_n dS,$ for $k = 1, 2, \dots, n-1$, and $U_n = 0$.

Output data (solution): $\mathbf{H}(\mathbf{r}), \mathbf{B}(\mathbf{r}), \mathbf{J}(\mathbf{r}), \mathbf{E}(\mathbf{r})$, in D

For unique potential $\mathbf{A}, V$: $n \cdot \mathbf{A} = A_n(P), \text{ on } S_H; V = f_D(P) \text{ on } S_D$

and gauged equation: $\text{grad}(\text{div} \mathbf{A}) \Rightarrow \text{div} \mathbf{A} = 0$

Eddy current problems: MG+MQS

- In most practical cases:
initial cond. $B(0)=0$
boundary conditions

$$S_H : H_t = n \times (H \times n) = 0 \Rightarrow n \times H = 0$$

$$S_B : B_n = n \cdot B = -b(r) \Rightarrow n \cdot B = 0$$

$$S_E : E_t = n \times (E \times n) = 0 \Rightarrow n \times E = 0$$

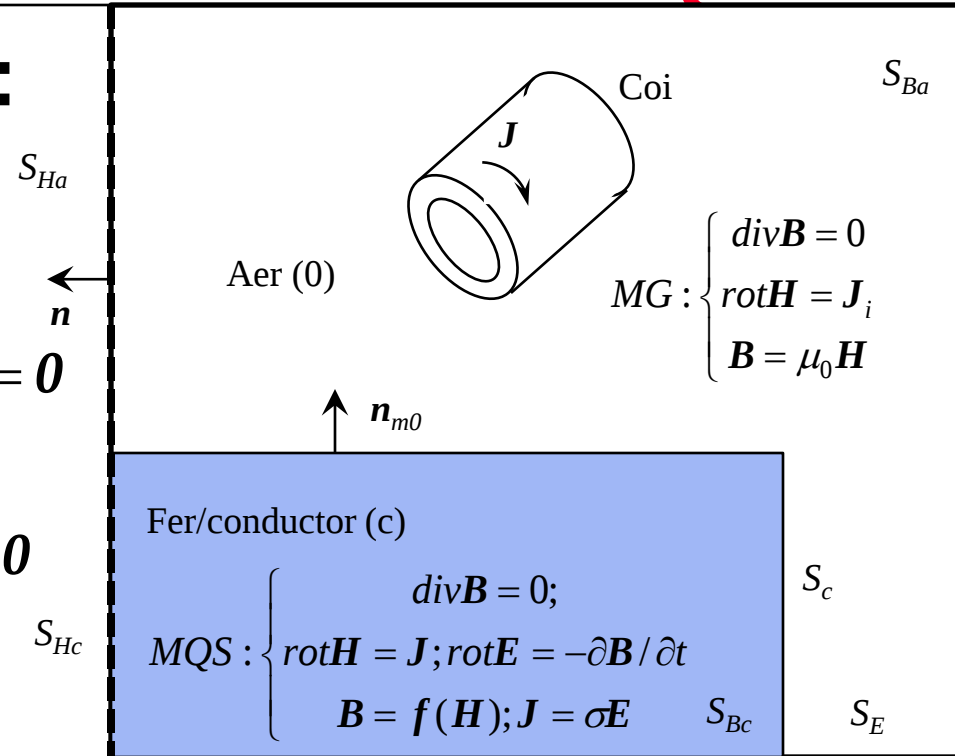
interface conditions

$$S_c : \nabla_s \times H = n_{12} \times (H_2 - H_1) = 0 \Rightarrow n_{ca} \times H_a = n_{ca} \times H_c \Rightarrow H_{ta} = H_{tc}$$

$$\nabla_s \cdot B = n_{12} \cdot (B_2 - B_1) = 0 \Rightarrow n_{ca} \cdot B_a = n_{ca} \cdot B_c \Rightarrow B_{na} = B_{nc}$$

$$\nabla_s \cdot J = n_{12} \cdot (J_2 - J_1) = 0 \Rightarrow 0 = n_{ca} \cdot J_a = n_{ca} \cdot J_c \Rightarrow J_{nc} = 0$$

$$\nabla_s \times E = n_{12} \times (E_2 - E_1) = 0 \Rightarrow n_{ca} \times E_a = n_{ca} \times E_c \Rightarrow E_{ta} = E_{tc}$$



Semnificatia conditiilor de frontiera

$S_{Ha} : \mathbf{H} \times \mathbf{n} = \mathbf{J}_s$, dar de obicei frontiera nu este pânză de curent și $S_{Hc} : \mathbf{H} \times \mathbf{n} = 0$,

condiție îndeplinită pe suprafețele de simetrie pe care liniile de câmp pica perpendicular sau la suprafața domeniilor feromagnetice ideale;

$S_B : \mathbf{n} \cdot \mathbf{B} = b$, dar de obicei $S_B : \mathbf{n} \cdot \mathbf{B} = 0$, condiție îndeplinită pe suprafețele de simetrie pe care liniile de câmp se preling fără să le traverseze, sau pe suprafețele aflate la depărtare suficient de mare, ca valoarea componentei normale a inducției să se anuleze.

$S_{Hc} : \mathbf{H} \times \mathbf{n} = 0$, condiție îndeplinită pe suprafețele de simetrie pe care liniile de câmp pică perpendicular sau la suprafața domeniilor feromagnetice ideale;

$S_E : \mathbf{n} \times \mathbf{E} = 0$, condiție îndeplinită pe suprafețele de simetrie sau nu, care sunt echipotențiale electric (de exemplu, pe electrozii de potențial cunoscut), pe care liniile de câmp electric pică perpendicular.

Consecință a acestor condiții, rezultă: $S_{Hc} : \mathbf{n} \cdot \mathbf{J} = 0$; $S_E : \mathbf{n} \cdot \mathbf{B} = 0$, ceea ce înseamnă că S_{Hc} este marginea conductorului spre un dielectric, iar S_E nu este traversată de linii ale câmpului magnetic.

Second order equations:

$$\begin{aligned}
 D_a : \left\{ \begin{array}{l} \mathbf{B} = \nabla \times \mathbf{A} \\ \nabla \times (\nu_0 \nabla \times \mathbf{A}) - \nabla \cdot (\nu_0 \nabla \cdot \mathbf{A}) = \mathbf{J}_0 \quad ; \\ \mathbf{H} = \nu_0 \nabla \times \mathbf{A} \end{array} \right. \\
 D_c : \left\{ \begin{array}{l} \mathbf{B} = \nabla \times \mathbf{A} \\ \nabla \times (\nu \nabla \times \mathbf{A}) - \nabla \cdot (\nu_0 \nabla \cdot \mathbf{A}) = \mathbf{J} - \nabla \times \mathbf{I} \\ \mathbf{E} = -\nabla V - \frac{\partial \mathbf{A}}{\partial t} \\ \mathbf{H} = \nu \mathbf{B} + \mathbf{I} \\ \mathbf{J} = \sigma \mathbf{E} \end{array} \right. \quad (2.60)
 \end{aligned}$$

Din care, după eliminarea densității de curent și a câmpului electric, se obțin ecuațiile:

$$\begin{aligned}
 D_c : \nabla \times (\nu \nabla \times \mathbf{A}) - \nabla \cdot (\nu_0 \nabla \cdot \mathbf{A}) + \sigma \left(\nabla V + \frac{\partial \mathbf{A}}{\partial t} \right) + \nabla \times \mathbf{I} &= 0; \\
 \nabla \cdot \left(\sigma \left(\nabla V + \frac{\partial \mathbf{A}}{\partial t} \right) \right) &= 0,
 \end{aligned} \quad (2.61)$$

satisfăcute de $\mathbf{A}$ - V în D_c , la care se adaugă ecuația potențialului $\mathbf{A}$ din D_a :

$$\nabla \times (\nu_0 \nabla \times \mathbf{A}) - \nabla \cdot (\nu_0 \nabla \cdot \mathbf{A}) = \mathbf{J}_0. \quad (2.62)$$

Boundary conditions for potentials:

$$S_{Ha} : \nu_0(\nabla \times \mathbf{A}) \times \mathbf{n} = \mathbf{J}_s; \quad \mathbf{n} \cdot \mathbf{A} = 0; \quad (2.63)$$

$$S_B : \mathbf{n} \times \mathbf{A} = \alpha; \quad \text{dar de obicei } S_B : \mathbf{n} \times \mathbf{A} = 0 \quad (2.64)$$

$$S_{Hc} : (\nu \nabla \times \mathbf{A} + \mathbf{I}) \times \mathbf{n} = 0; \quad \mathbf{n} \cdot \left(\nabla V + \frac{\partial \mathbf{A}}{\partial t} \right) = 0 \quad (2.65)$$

$$S_E : \mathbf{n} \times \left(\nabla V + \frac{\partial \mathbf{A}}{\partial t} \right) = 0; \quad \mathbf{n} \times \mathbf{A} = 0; \quad V = V_0; \quad (2.66)$$

$$\begin{aligned} S_{ac} : \mathbf{n}_c \cdot (\nabla \times \mathbf{A}_a - \nabla \times \mathbf{A}_c) &= 0; \\ \mathbf{n}_c \times (\nu_0(\nabla \times \mathbf{A}_a) - \nu \nabla \times \mathbf{A}_c + \mathbf{I}) &= 0; \\ \mathbf{n}_c \cdot \left(\nabla V + \frac{\partial \mathbf{A}_c}{\partial t} \right) &= 0. \end{aligned} \quad (2.67)$$

Weak form of gauged field

Forma slabă a acestor ecuații, în care potențialul vector satisface implicit condiția de etalonare Coulomb este:

$$\begin{aligned}
 & \int_{D_a} (\nu_0 (\nabla \times \mathbf{W}) \cdot (\nabla \times \mathbf{A}) + \nu_0 \nabla \cdot \mathbf{W} \nabla \cdot \mathbf{A}) d\Omega + \\
 & + \int_{D_c} \left(\nu (\nabla \times \mathbf{W}) \cdot (\nabla \times \mathbf{A}) + \nu \nabla \cdot \mathbf{W} \nabla \cdot \mathbf{A} + \sigma \mathbf{W} \cdot \left(\nabla V + \frac{\partial \mathbf{A}}{\partial t} \right) \right) d\Omega = \\
 & \int_{D_a} \mathbf{W} \cdot \mathbf{J}_0 d\Omega - \int_{D_c} (\nabla \times \mathbf{W}) \cdot \mathbf{I} d\Omega + \int_{S_{Ha}} \mathbf{W} \cdot \mathbf{J}_s dS \\
 - & \int_{D_c} \sigma \nabla N \cdot \left(\nabla V + \frac{\partial \mathbf{A}}{\partial t} \right) d\Omega = 0
 \end{aligned} \tag{2.68}$$

Aici s-a notat cu $\mathbf{W}$ o funcție arbitrară de test vectorială și cu N o funcție arbitrară de test scalară, dar care satisfac următoarele condiții esențiale de frontieră:

$$S_{Hc} \cup S_{Ha} : \mathbf{n} \cdot \mathbf{W} = 0; \quad S_E \cup S_B : \mathbf{n} \times \mathbf{W} = 0; \quad S_E : N = 0. \tag{2.69}$$

Dacă domeniul conductor are conductivitatea σ constantă, atunci potențialul scalar V poate fi ales nul, iar soluția problemei este dată doar de potențialul vector $\mathbf{A}$, definit în întregul domeniu de calcul.

There is not an energy functional!!!!

Weak form of un-gauged field

vector etalonat. Deoarece din ecuații dispar în acest caz cei doi termeni, care se referă la divergența potențialului vector, ei dispar și din forma slabă neetalonată, care devine mai simplă:

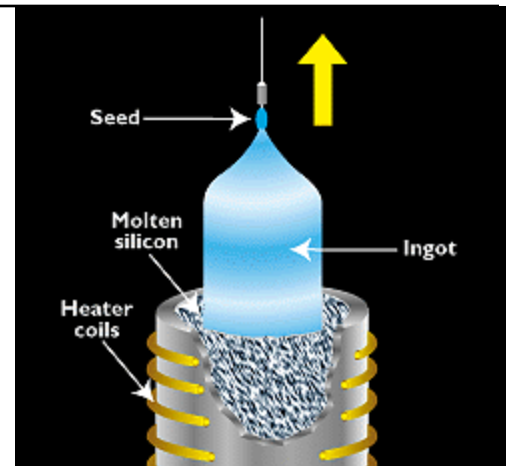
$$\begin{aligned}
 & \int_{D_a} \nu_0 (\nabla \times \mathbf{W}) \cdot (\nabla \times \mathbf{A}) d\Omega + \\
 & + \int_{D_c} \left(\nu (\nabla \times \mathbf{W}) \cdot (\nabla \times \mathbf{A}) + \sigma \mathbf{W} \cdot \left(\nabla V + \frac{\partial \mathbf{A}}{\partial t} \right) \right) d\Omega = \quad (2.70) \\
 & = \int_{D_a} (\nabla \times \mathbf{W}) \cdot \mathbf{T}_0 d\Omega - \int_{D_c} (\nabla \times \mathbf{W}) \cdot \mathbf{I} d\Omega.
 \end{aligned}$$

Pentru a descrie curenții sursă, aici s-a folosit potențialul lor vector $\mathbf{T}_0$:

$$\nabla \times \mathbf{T}_0 = \begin{cases} \mathbf{J}_0 & \text{în } D_a \\ 0 & \text{în } D_a \end{cases} \quad \text{cu } \mathbf{T}_0 \times \mathbf{n} = \mathbf{J}_s \text{ pe } S_{Ha}. \quad (2.71)$$

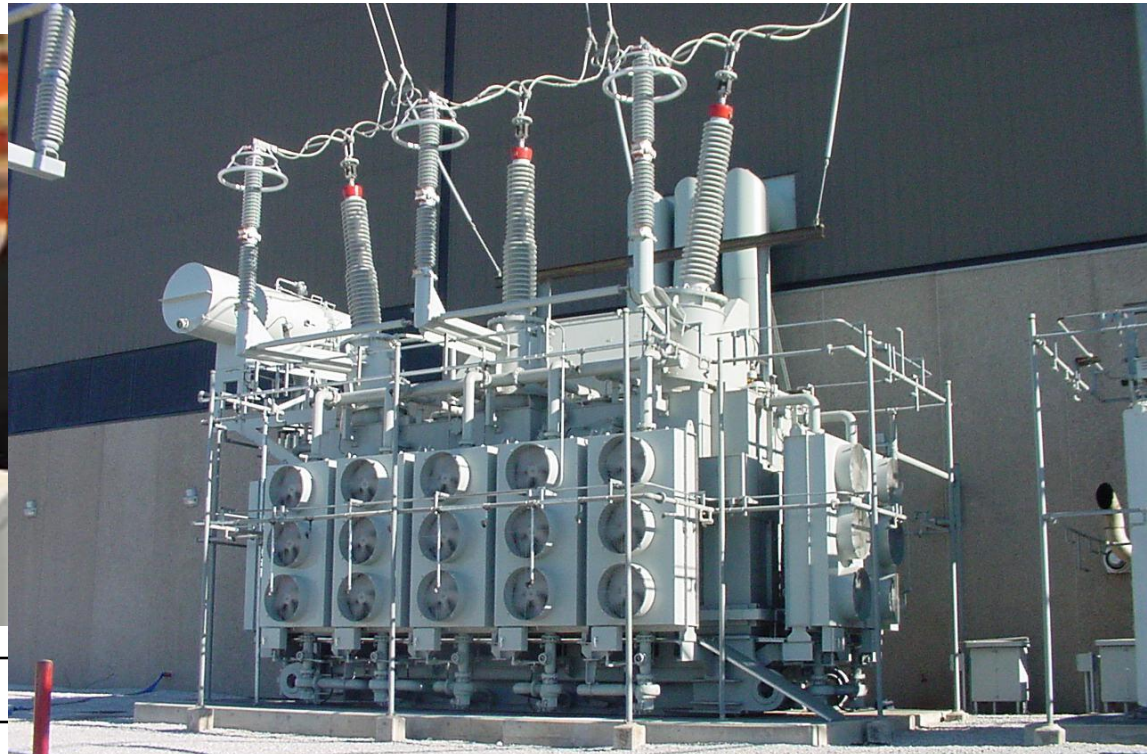
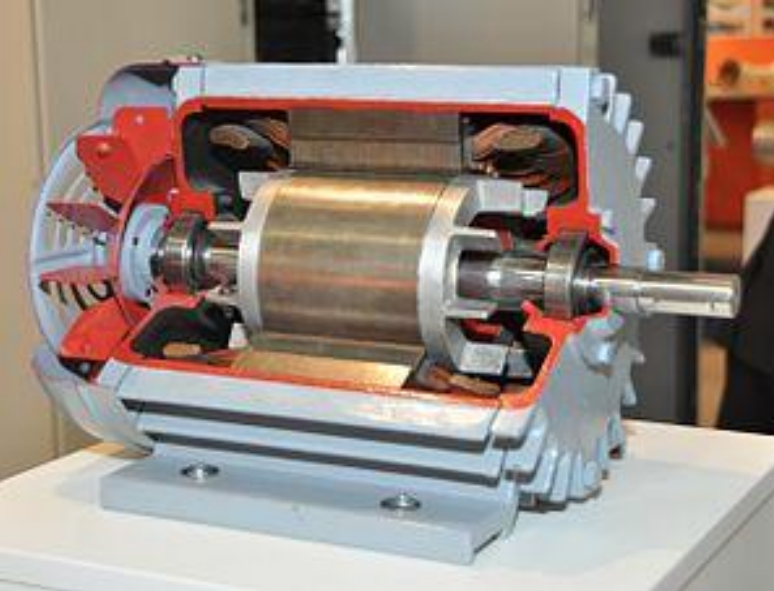
- **Transformers**
- **Induction motors**
- **Electric generators**
- **Eddy currents breaks**
- **Inductive heating**
- **Meters – inductions counters**
- **Eddy currents testing**

Inductive heating

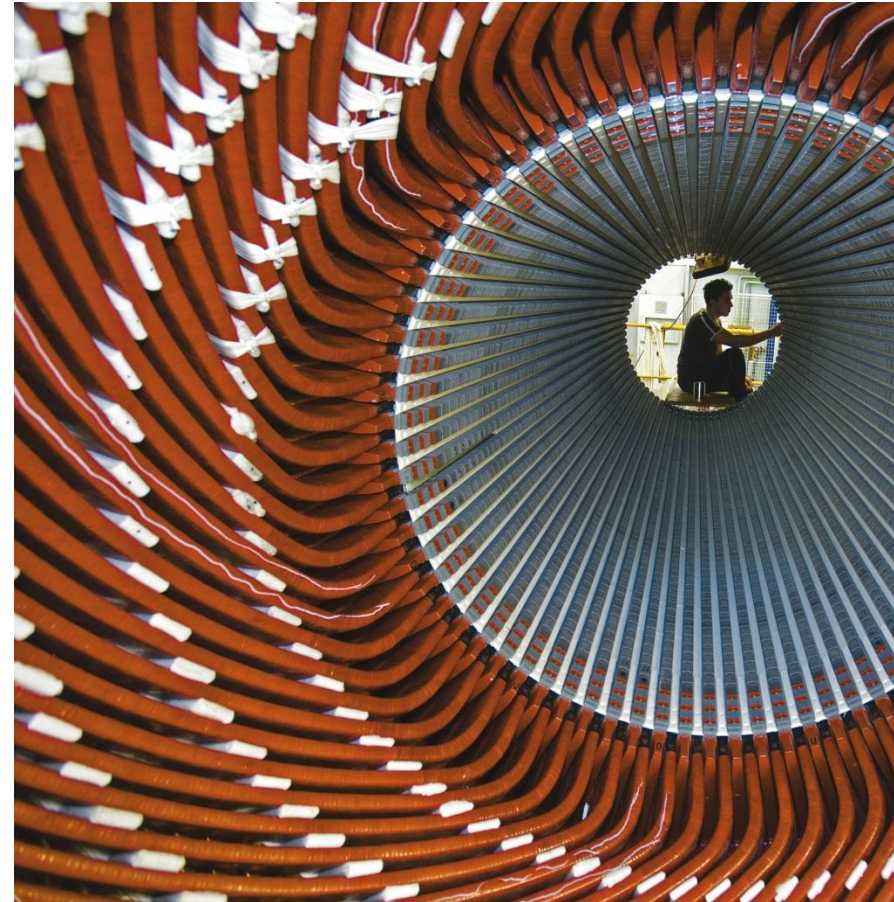
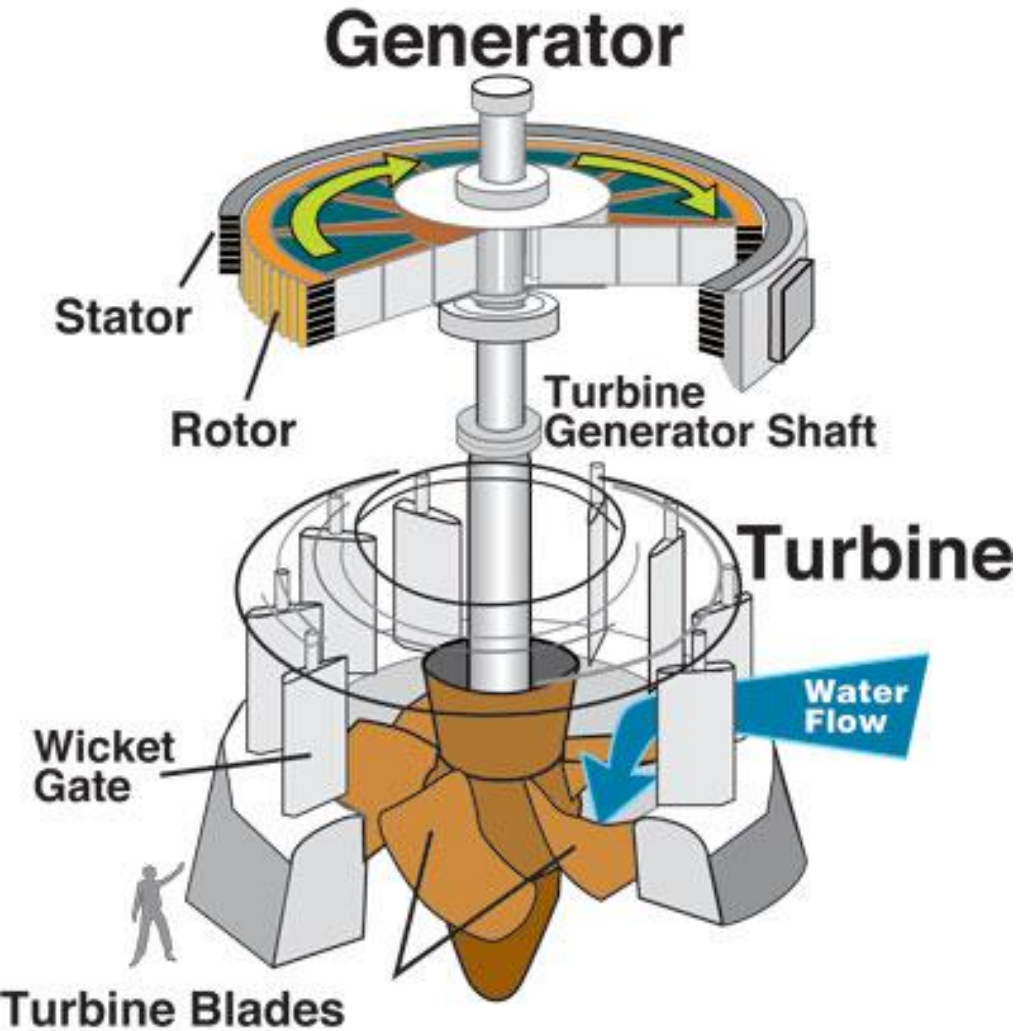


MQS applications:

Counters, motors, trafos

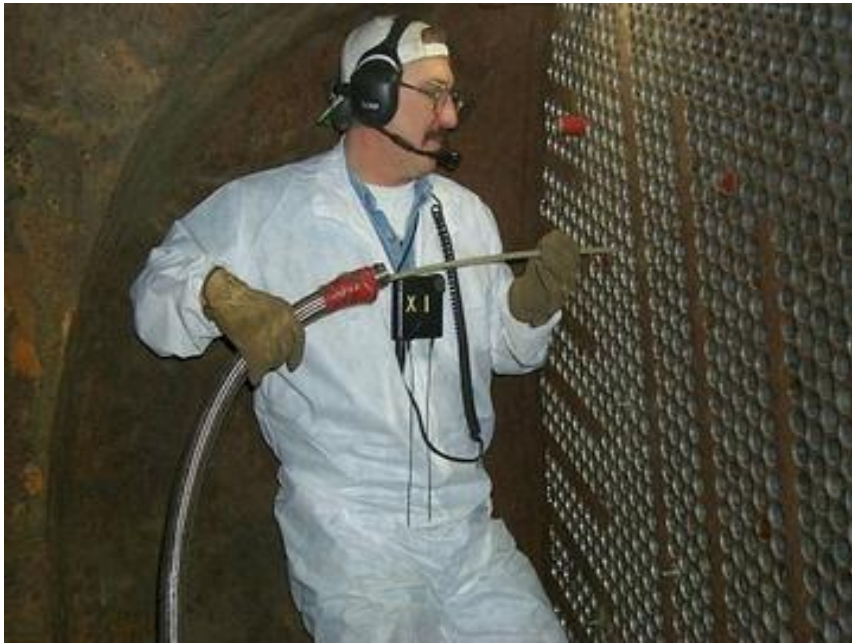


Hydro- and turbo-generators



Eddy current testing

- Nuclear plants



Air crafts



Not so easy questions, for curious people

1. How are first order MQS equations?
2. What type of potentials may be defined in MQS regime?
3. How are the second order equations for these potentials?
4. How are the boundary conditions for each potential to be unique?
5. How may be proven the uniqueness theorem?
6. What are MQS boundary conditions in semi-bounded domains?
7. How may be defined magnetic circuits in MQS regime?
8. What space may be used for trial and test functions in weak MQS formulation?
9. How are the integral equations of MQS field?
10. What about solution existence? What is a curl-curl operator?
11. What about nonlinear magnetic materials?
12. What about hysteresis?
13. What are the main novelties and difficulties of MQS regime, compared with static and steady state regimes?
14. Which of TEAM benchmarks are MQS problems?